

Torsdag d. 18. marts, kl. 13-14:30 (ONLINE)

Forskningsenheden for Robophilosophy

Johanna Seibt:

Towards a Descriptive Framework for Human-Robot Interactions

Abstract: Based on a brief review of the state of the art on the topic, the talk will introduce the basic ideas of the framework OASIS (Ontology of Asymmetric Social Interaction). The aim of the OASIS framework is to provide the tools for a differentiated description of the goings-on in human-robot interaction from several perspectives. A central element of OASIS is the notion of "sociomorphing" (based on collaborative research with C. Vestergaard and M. Damholdt): while Human-Robot Interaction research by default assumes that people anthropomorphize robots, it appears that another type of human mental operation guides us in experiencing robots and interacting with them, at least in certain cases. Attention to different types of sociomorphing offers a pathway towards describing in greater detail different types of experienced sociality in human-robot interaction.

Please contact Johanna for the zoom link.

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